

Rotation

- Angular variables and rotational kinematics

Displacement	Velocity	Acceleration
x (meters)	v (m/s)	a (m/s ²)
θ (radians)	ω (rad/s)	α (rad/s ²)

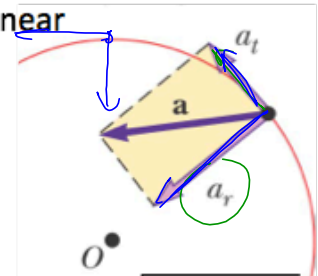
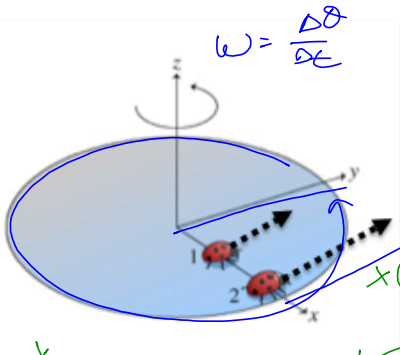
$$\omega = \omega_o + \alpha t$$

$$\theta = \theta_o + \omega_o t + \frac{1}{2} \alpha t^2$$

$$v^2 = v_o^2 + 2a(x-x_o) \quad x = \frac{1}{2}(v_o + v)t$$

- All points on the wheel - same angular velocity (ω) and angular acceleration (α)

- Different linear velocity and linear acceleration (tangential)
- (as if they were to fly off)
 - faster, farther out



$$v = r\omega$$

$$a_r = \frac{v^2}{r} = r\omega^2$$

$$a_t = r\alpha$$

$$a_c = \frac{v^2}{r} = \frac{r^2 \omega^2}{r} = r\omega^2$$

$$a = \sqrt{a_r^2 + a_t^2}$$

Rotation

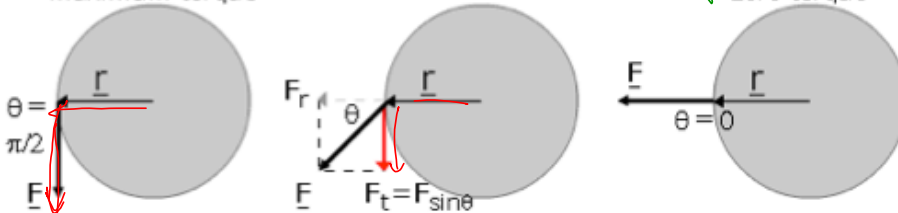
- Torque – Turning power, similar to Force (F)

$$\tau = r \perp F = rF \sin \theta$$

- Unit: m N

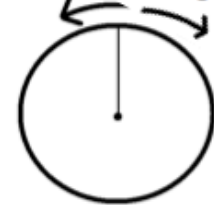
$w = r \cdot \omega$
 zero torque

maximum torque



Directions

Positive Negative



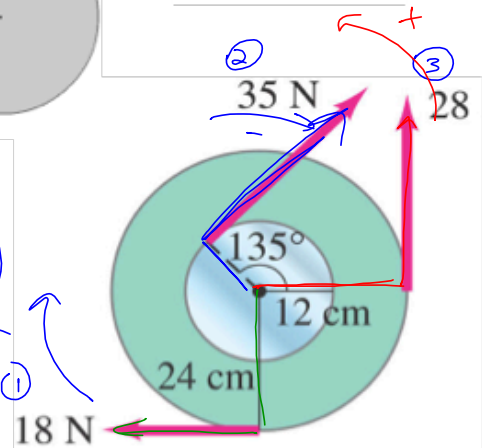
$F = m a$
 $\tau = I \cdot \alpha$

$\Sigma T = T_3 - T_1 - T_2$
 $\Sigma T = (0.24)(28) - (0.24)(18) - (0.12)(35)$

- 'F = ma'
- I = Moment of inertia

$r \times F = I \cdot \alpha$

$I = \Sigma m r^2$



Rotation Example

A rigid bar with a mass M and length L is free to rotate about a frictionless hinge on a wall. The bar has a moment of inertia of $I = \frac{1}{3}ML^2$ around the hinge and is released from rest from an initially horizontal position as shown. What is the angular acceleration of the bar when it makes a 30.0° angle to the vertical also as shown?

A.) $\frac{g}{3L}$

B.) $\frac{2g}{3L}$

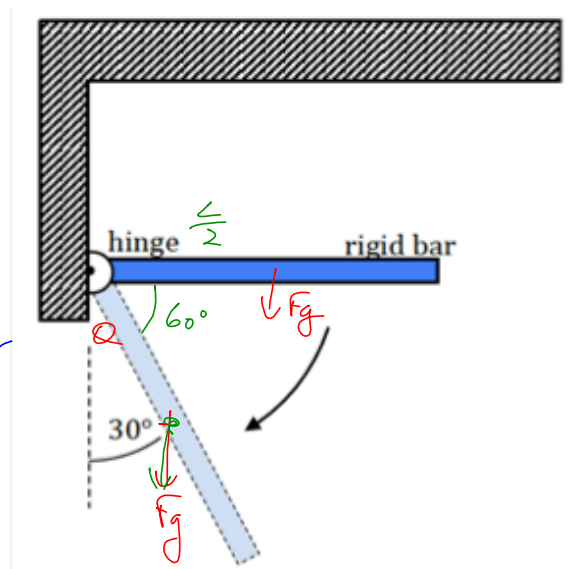
C.) $\frac{g}{L}$

D.) $\frac{3g}{4L}$

E.) $\frac{3g}{2L}$

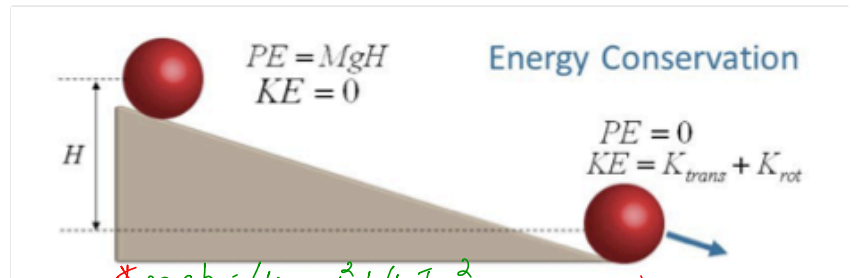
$I = \frac{1}{3}ML^2$ M
 L
 $\alpha = ?$

$\tau = I \cdot \alpha$
 $I = \frac{1}{3}ML^2 \cdot \alpha$
 $rF \sin \theta = \frac{1}{3}ML^2 \cdot \alpha$
 $\frac{L}{2} \cdot Mg \sin 30^\circ = \frac{1}{3}ML^2 \cdot \alpha$
 $\frac{L}{2} \cdot g \cdot \frac{1}{2} = \frac{1}{3} \cdot L^2 \cdot \alpha$
 $\frac{1}{4}g = \frac{1}{3}L \cdot \alpha$
 $\frac{3}{4}g = \frac{L}{3} \alpha$

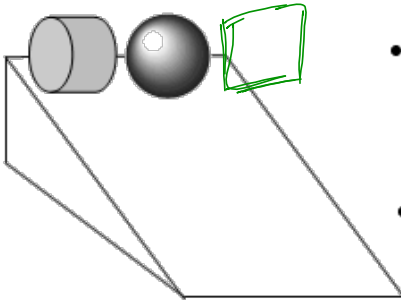


Rotation

- Rotational Kinetic Energy: $\frac{1}{2} I \omega^2$



- Gravitational potential converted into translational & rotational KE



- Smallest moment of inertia wins – easier to begin rotation

- Of a cylinder, solid sphere, and a box, which would win? Why?

Rotation

- Angular momentum – tendency of an object to continue rotation.

+ Conservation of angular momentum

$$L = I \cdot \omega$$

$$L_o = L_f = \text{constant}$$

- Alternate formulas:

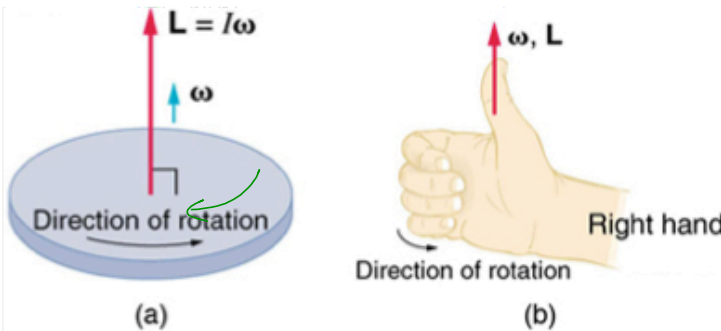
$$L = mrv$$

$$L = I \cdot \omega = mr^2 \cdot \frac{v}{r}$$

$$\tau = \frac{\Delta L}{\Delta t}$$

Impulse-Momentum Theory

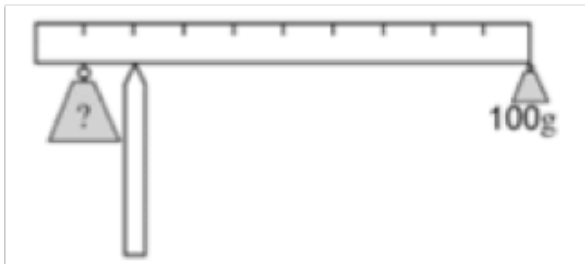
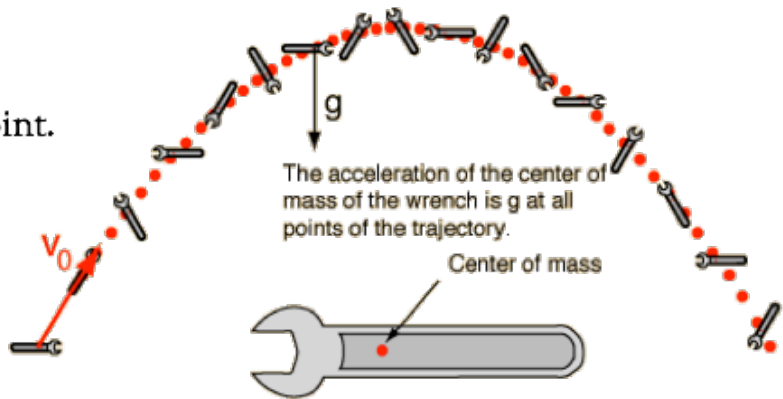
- **Direction of angular momentum and additional torque



*Center of Mass

- Average mass of an object condensed into a single point.
Average location of mass

$$x_{CM} = \frac{\sum_i m_i x_i}{M} \quad y_{CM} = \frac{\sum_i m_i y_i}{M}$$



A 100.0 g mass is placed at one end of a 100.0 g meter stick. If the meter stick is said to be balanced on a pivot point at the 20.0 cm mark as shown, how much mass must be at the 10.0 cm mark?